ICE-2231
(Data Structure)

Lecture on
Graphs

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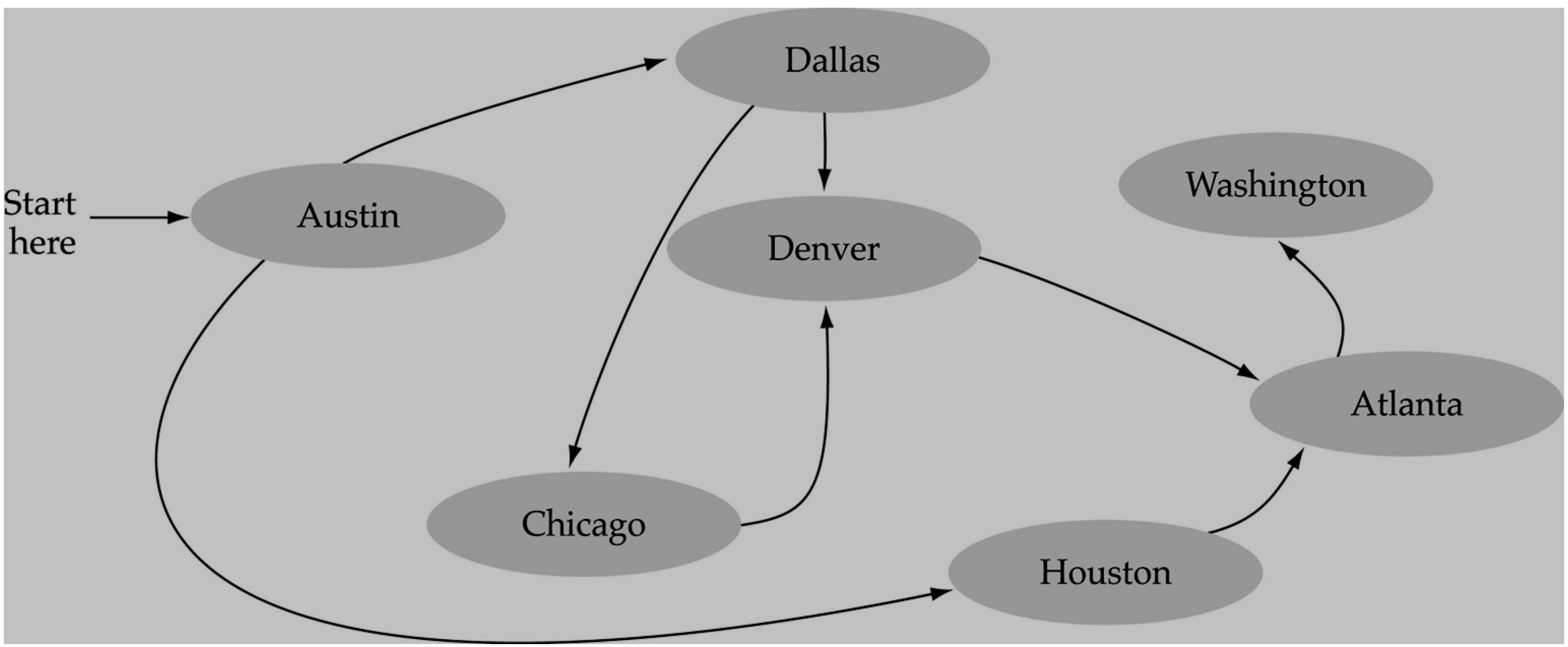
Trees and Graphs: Basic terminology, Binary trees, Binary tree representation, Tree traversal algorithms, Extended binary tree, Huffman codes/algorithm, Graphs, Graph representation, Shortest path algorithm and transitive closure, Traversing a graph.

What is Graph?

- A data structure that consists of a set of nodes (*vertices*) and a set of edges that relate the nodes to each other.

- The set of edges describes relationships among the vertices



What is Graph?

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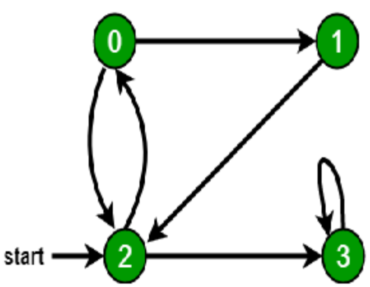
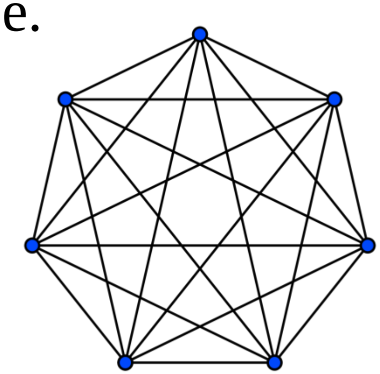
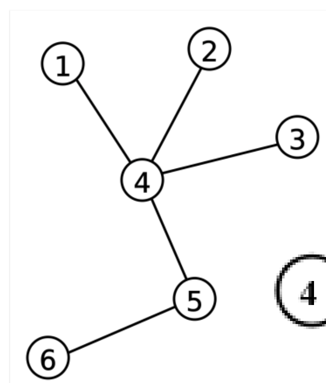
- A graph **G** consists of two things:
  - A set **V** of elements called nodes (or points or vertices)
  - A set **E** of edges such that each edge **e** in **E** is identified with a unique (unorder) pair [**u,v**] of nodes in **V**, denoted by e= [**u,v**].
- Sometimes the parts of a graph is indicated by writing **G=(V, E)**
  - *V(G)*: a finite, nonempty set of vertices
  - *E(G)*: a set of edges (pairs of vertices)

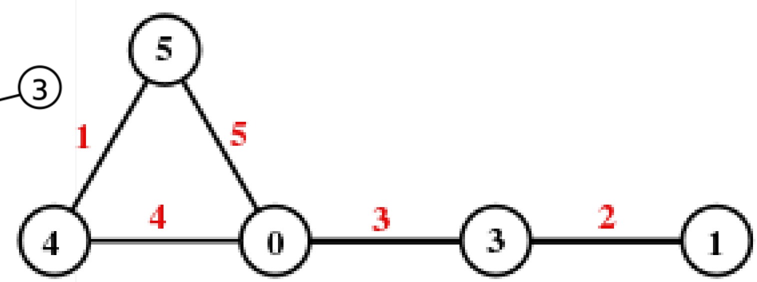
Connected, Complete, Tree, Labeled Graph

- A graph G is Connected if and only if there is a simple path between any two nodes in G.
- A graph G is said to be Complete if every node u in G is adjacent to every other node v in G.
    - A complete graph with n nodes will have (n-1)/2 edges.
- A connected graph T without any circle is called a Tree graph or free tree or, simply, a tree.
- A graph G is said to be Labeled if its edges are assigned data,
    - In particular, G is said to be weighted if each edge e in G is assigned a nonnegative numerical value w(e) called the weight or length of e.









Assignement

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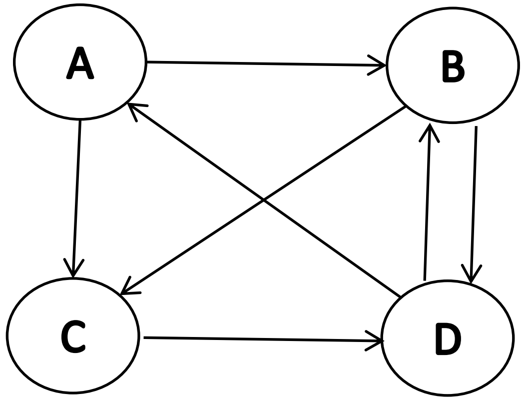
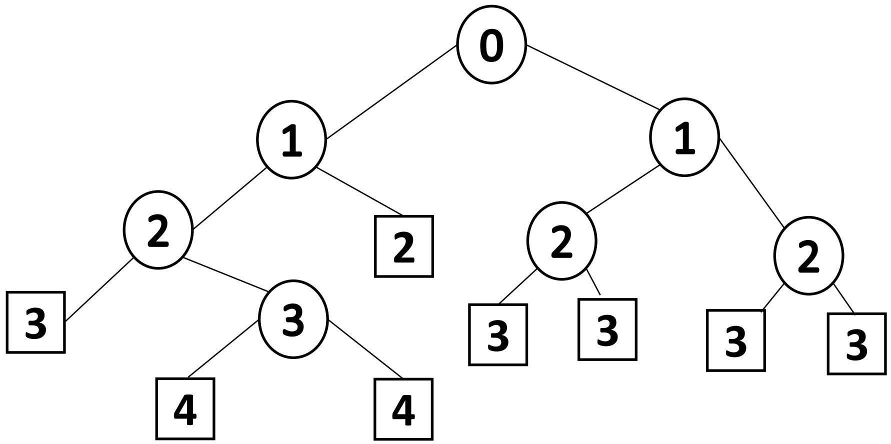
Presentation on Example: 8.1

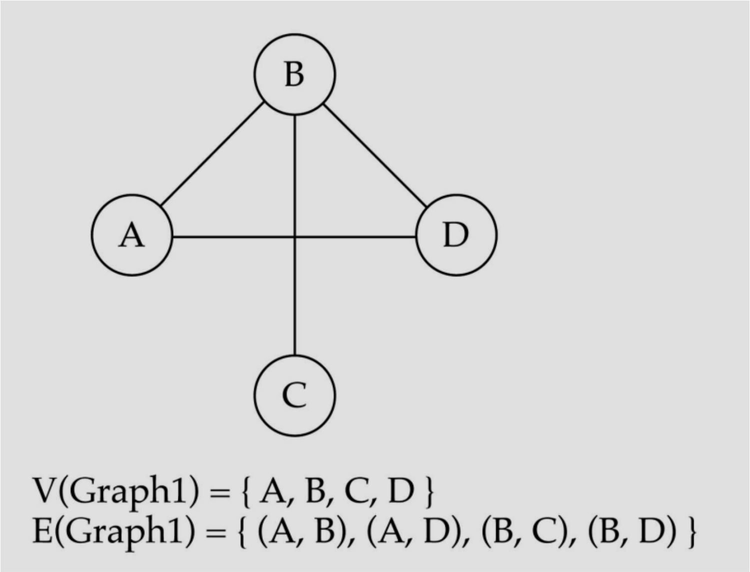


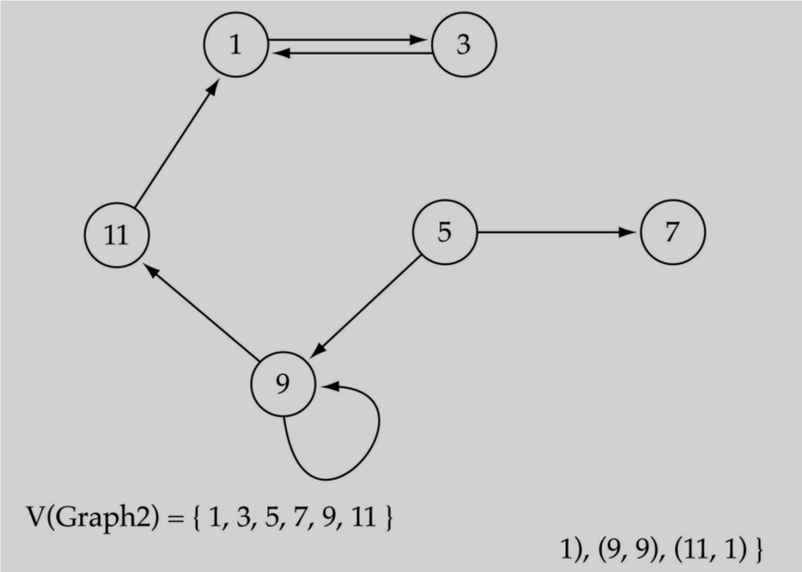


Undirected vs. Directed Graphs

- When the edges in a graph have no direction, the graph is called *undirected*

- When the edges in a graph have a direction, the graph is called *directed* (or *digraph*)





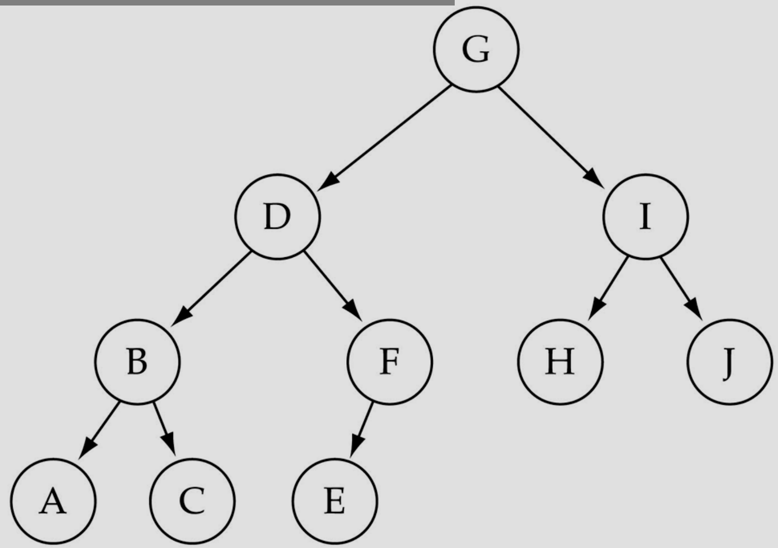
Directed Graphs

- Suppose G is a directed graph with a directed edge e=(u,v).
  - E begins at u and ends at v
  - u is the origin or initial point of e, and v is the destination or terminal point of e
  - u is a predecessor of v, and v is a successor or neighbor of u.
  - u is adjacent to v, and v is adjacent to u.
- A directed graph G is said to be connected, or strongly connected, if for each pair u, v of nodes in G there is a path from u to v, and there is also a path from v to u.

Tree vs. Graph

- Trees are special cases of graphs!!

Tree is a directed graph



V(Graph3) = { A, B, C, D, E, F, G, H, I, J }
E(Graph3) = { (G, D), (G, J), (D, B), (D, F) (I, H), (I, J), (B, A), (B, C), (F, E) }

Graph Representation

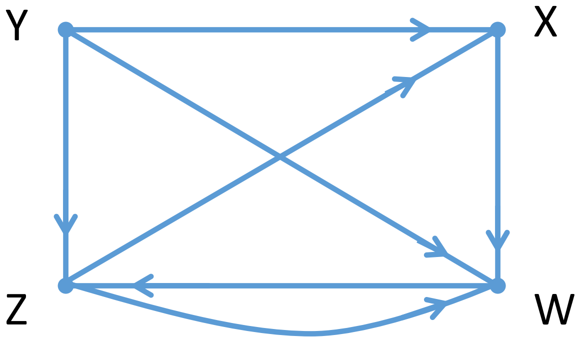
- There are two standard ways of maintaining a graph G in the computer memory:
  - The Sequential Representation of G, is by means of its adjacency matrix, A
  - The Linked representation of G, is by means of linked lists of neighbors.

Graph Representation: Adjacency Matrix

- G is a simple directed graph with $v_1, v_2, \ldots., v_m$ vertices
- $A = (a_{ij})$ is the adjacency matrix of G where,

Example 8.3

X Y Z W

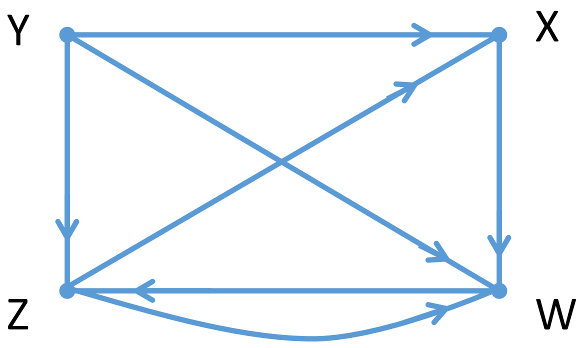


Graph Representation: Path Matrix

- G is simple directed graph with m nodes v_1, v_2, …., v_m. Then the path matrix $P = (p_{ij})$ defined as

- Simple Path: Path from v_i to v_j and $v_i \neq v_j$
- Cycle: Path from v_i to v_j and $v_i = v_j$
- $p_{ij} = 1$ if and only if there is a nonzero number in ij entry of the matrix $B_m = A + A^2 + A^3 + \ldots + A^m$

Graph Representation: Path Matrix

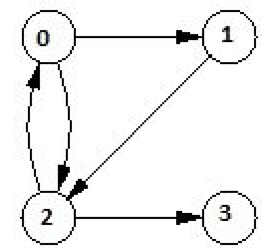


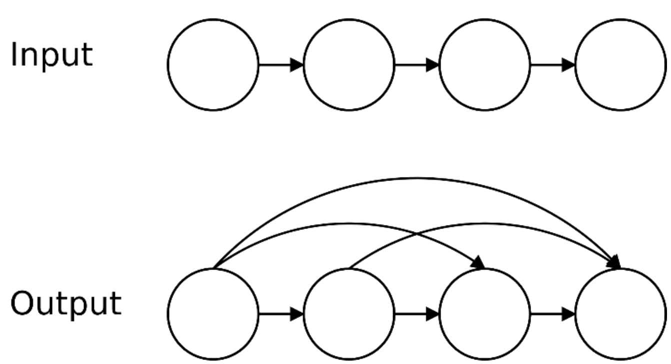
Thus, and

Transitive Closure

- The transitive closure of a graph G is defined to be the graph G’ such that G’ has the same node as G and there is an edge (v_i,v_j) in G’ whenever there is a path from v_i to v_j in G.
- Given a directed graph, find out if a vertex j is reachable from another vertex i for all vertex pairs (i, j) in the given graph.
- Here reachable mean that there is a path from vertex i to j. The reach-ability matrix is called the transitive closure of a graph.
- For example, consider below graph

$$\begin{matrix} 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 \end{matrix}$$



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Transitive closure of above graphs is
     1 1 1 1
     1 1 1 1
     1 1 1 1
     0 0 0 1
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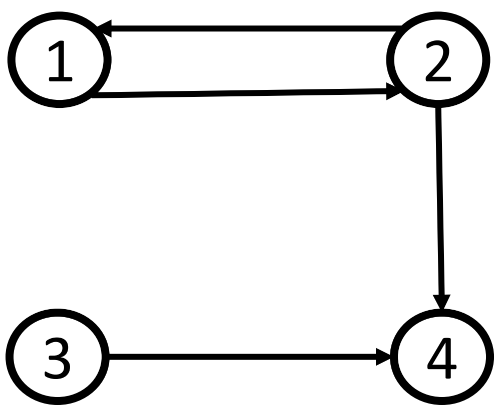
Example 1

Let A = {1, 2, 3, 4}, and let

R = {(1,2), (2,3), (3,4), (2,1)}.

Find the transitive closure of R.



Transitive Closure

Let ***R*** be a relation on a set A. Let R^{∞} be the transitive closure of ***R.***

Three methods for finding :

a) Digraph Approach

b) Adjacency Matrix method

c) Warshall's Algorithm

Warshall's Algorithm for Path Matrix

- Let G be a directed graph with m nodes v1,v2, v3,….vm. Suppose we want to find the path matrix P of the graph G.
- Warshall's algorithm is much more efficient than calculating the powers of the adjacency matrix A.
- First we define m-square Boolean matrices P_0, P_1, P_2,,… P_m as follows.
- Let $P_k[i,j]$ denote ij entry of the matrix P_k. Then

If there is a simple path from v_i to v_j which does not use any other nodes except possible v_1, v_2, ….., v_k

Solution

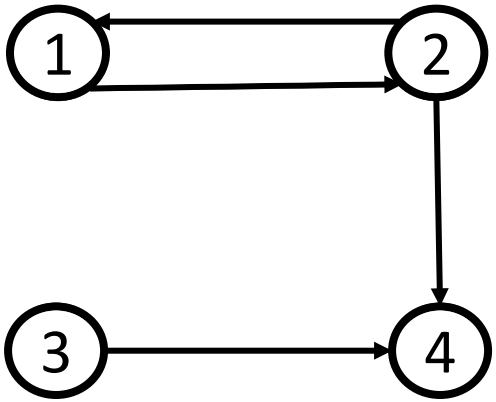
Let A = {1, 2, 3, 4}, and let R = {(1,2), (2,3), (3,4), (2,1)}.

Find the transitive closure of R.

Warshall's Algorithm

convert R to M_R

R = {(1,2), (2,3), (3,4), (2,1)} ➡



Warshall's Algorithm for Path Matrix

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- $P_0[i,j] = 1$ if there is an edge from v_i to v_j
- $P_1[i,j] = 1$ if there is a simple path from v_i to v_j which does not use any other nodes except possibly v_1.
- $P_2[i,j] = 1$ if there is a simple path from v_i to v_j which does not use any other nodes except possibly v_1, v_2.
- The element of P_k can be obtained as

Warshall's Algorithm for Path Matrix

- G: directed graph, A: adjacency matrix, M: Nodes

1. Repeat for I,J = 1,2,….,M

   If A[I,J] == 0 then set P[I,J] = 0

   Else set P[I,J] = 1

2. Repeat steps 3 and 4 for K = 1,2,…,M

3. Repeat step 4 for I = 1,2,…., M

4. Repeat for J = 1,2,…..,M

   Set $P[I,J] = P[I,J] \vee (P[I,K] \wedge P[K,J])$

5. Exit

Shortest Path Algorithm

- Let G be a directed graph with m nodes, $v_1, v_2, \ldots\ldots, v_m$.
- Suppose G is weighted, and $w(e)$ is called the weight or length of the edge e.
- Then the weigth matrix $W = (w_{ij})$ is defined as:
- We want to find the shortest path matrix $Q = (q_{ij})$:

  q_{ij} = length of the shortest path from v_i to v_j

Shortest Path Algorithm

- We define sequence of matrices $Q_0, Q_1, \ldots\ldots, Q_m$ (like $P_0, P_1, \ldots\ldots P_m$), whose entries are:

$$Q_k[i.j] = MIN(Q_{k-1}[i,j], Q_{k-1}[i,k] + Q_{k-1}[k,j])$$

- Q_0 is same as the weight matrix W where the 0 is replaced by the infinity (∞)
- The final matrix Q_m will be the desired matrix Q

Shortest Path Algorithm

- G: directed weighted graph, W: weight matrix, M: Nodes

1. Repeat for I,J = 1,2,….,M

    If W[I,J] == 0 then set Q[I,J] = ∞

    Else set Q[I,J] = W[I,J]

2. Repeat steps 3 and 4 for K = 1,2,…,M

    3. Repeat step 4 for I = 1,2,…., M

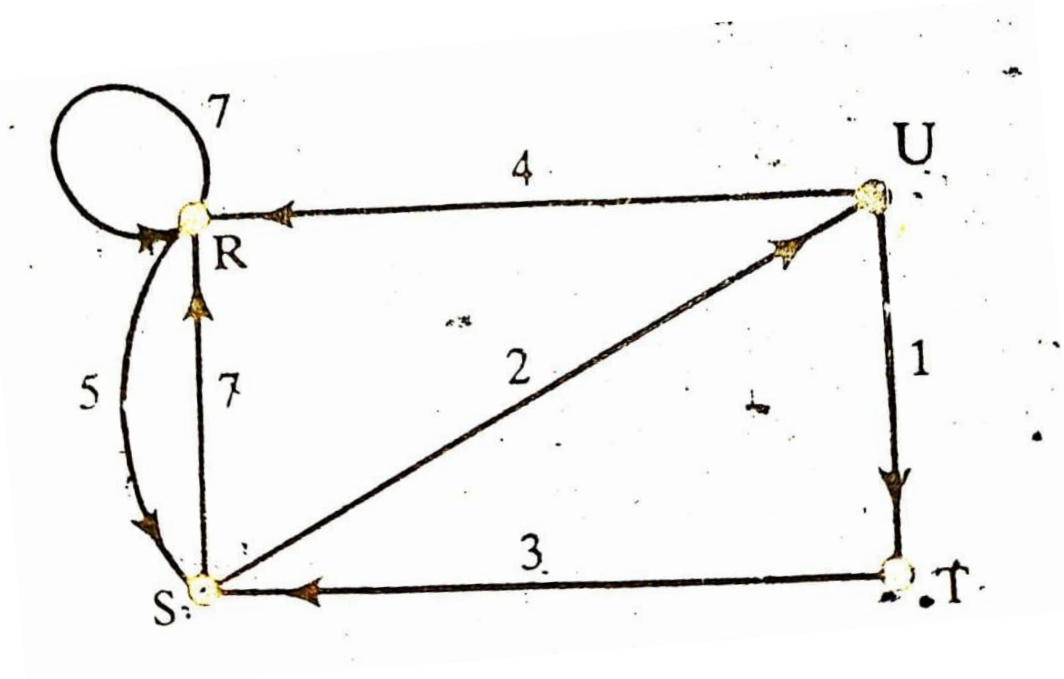
        4. Repeat for J = 1,2,…..,M

            Set Q[I,J] = MIN(Q[I,J], Q[I,K] + Q[K,J])

5. Exit

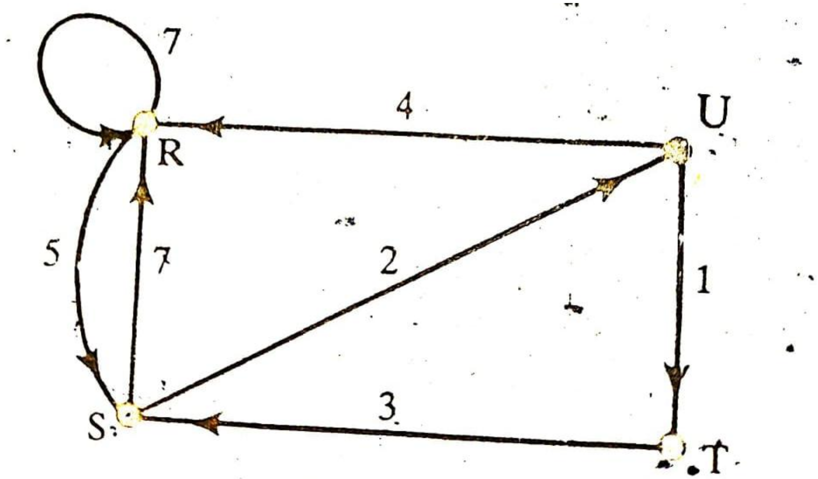
Shortest Path Algorithm: Example

- Consider the following weighted graph:
- Assume v_1=R, v_2=S, v_3=T, and v_4=U
- Then the weighted matrix W of G is as follows:



$$
W = \begin{array}{c@{}c}
\begin{array}{cccc} \mathbf{R} & \mathbf{S} & \mathbf{T} & \mathbf{U} \end{array} & \\
\begin{pmatrix} 7 & 5 & 0 & 0 \\ 7 & 0 & 0 & 2 \\ 0 & 3 & 0 & 0 \\ 4 & 0 & 1 & 0 \end{pmatrix} & \begin{array}{c} \mathbf{R} \\ \mathbf{S} \\ \mathbf{T} \\ \mathbf{U} \end{array}
\end{array}
$$

Shortest Path Algorithm: Example



$$W = \begin{array}{c|c} & \begin{array}{cccc} R & S & T & U \end{array} \\ \hline & \\ \end{array}$$

$$\begin{array}{cc} & \begin{array}{cccc} \mathbf{R} & \mathbf{S} & \mathbf{T} & \mathbf{U} \end{array} \\ W = & \begin{pmatrix} 7 & 5 & 0 & 0 \\ 7 & 0 & 0 & 2 \\ 0 & 3 & 0 & 0 \\ 4 & 0 & 1 & 0 \end{pmatrix} \begin{array}{c} \mathbf{R} \\ \mathbf{S} \\ \mathbf{T} \\ \mathbf{U} \end{array} \end{array}$$

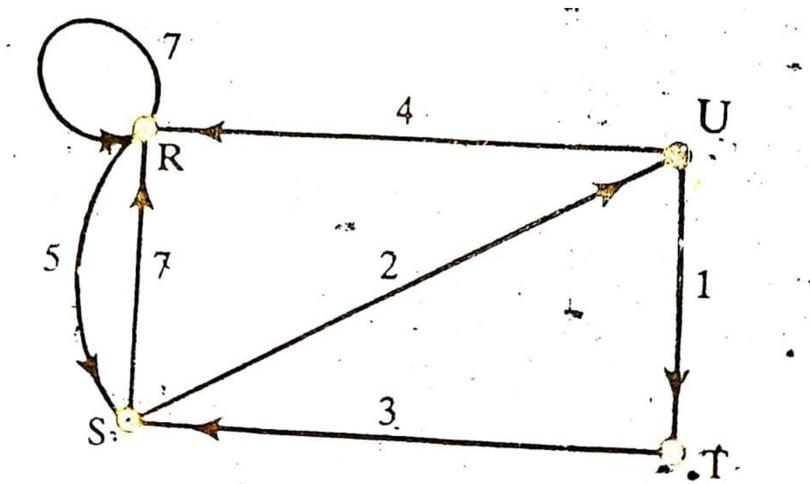
• Applying the modified Warshall's algorithm, we obtain the following matrices:

$$Q_0 = \begin{pmatrix} 7 & 5 & \infty & \infty \\ 7 & \infty & \infty & 2 \\ \infty & 3 & \infty & \infty \\ 4 & \infty & 1 & \infty \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & - \\ SR & - & - & SU \\ - & TS & - & - \\ UR & - & UT & - \end{pmatrix}$$

$$Q_1 = \begin{pmatrix} 7 & 5 & \infty & \infty \\ 7 & 12 & \infty & 2 \\ \infty & 3 & \infty & \infty \\ 4 & 9 & 1 & \infty \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & - \\ SR & SRS & - & SU \\ - & TS & - & - \\ UR & URS & UT & - \end{pmatrix}$$

$$Q_1[4, 2] = \mathrm{MIN}(Q_0[4, 2],\ Q_0[4, 1] + Q_0[1, 2]) = \mathrm{MIN}(\infty, 4 + 5) = 9$$

Shortest Path Algorithm: Example



$$W = \begin{array}{c|c} & \begin{array}{cccc} R & S & T & U \end{array} \\ \begin{array}{c} R \\ S \\ T \\ U \end{array} & \begin{pmatrix} 7 & 5 & 0 & 0 \\ 7 & 0 & 0 & 2 \\ 0 & 3 & 0 & 0 \\ 4 & 0 & 1 & 0 \end{pmatrix} \end{array}$$

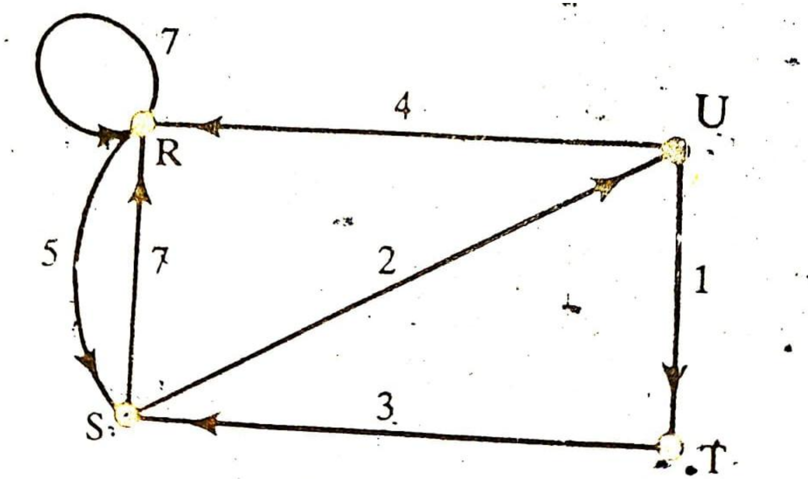
- Applying the modified Warshall's algorithm, we obtain the following matrices

$$Q_1 = \begin{pmatrix} 7 & 5 & \infty & \infty \\ 7 & 12 & \infty & 2 \\ \infty & 3 & \infty & \infty \\ 4 & 9 & 1 & \infty \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & - \\ SR & SRS & - & SU \\ - & TS & - & - \\ UR & URS & UT & - \end{pmatrix}$$

$$Q_2 = \begin{pmatrix} 7 & 5 & \infty & 7 \\ 7 & 12 & \infty & 2 \\ 10 & 3 & \infty & 5 \\ 4 & 9 & 1 & 11 \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & RSU \\ SR & SRS & - & SU \\ TSR & TS & - & TSU \\ UR & URS & UT & URS \end{pmatrix}$$

$$Q_2[1, 3] = \mathrm{MIN}(Q_1[1, 3],\ Q_1[1, 2] + Q_1[2, 3]) = \mathrm{MIN}(\infty, 5 + \infty) = \infty$$

Shortest Path Algorithm: Example



$$W=\begin{array}{c} \\ \\ \\ \\ \end{array}\begin{array}{c}\begin{matrix} \quad R & \quad S & \quad T & \quad U \end{matrix}\\ \begin{pmatrix} 7 & 5 & 0 & 0 \\ 7 & 0 & 0 & 2 \\ 0 & 3 & 0 & 0 \\ 4 & 0 & 1 & 0 \end{pmatrix}\end{array}\begin{array}{c} \\ R \\ S \\ T \\ U \end{array}$$

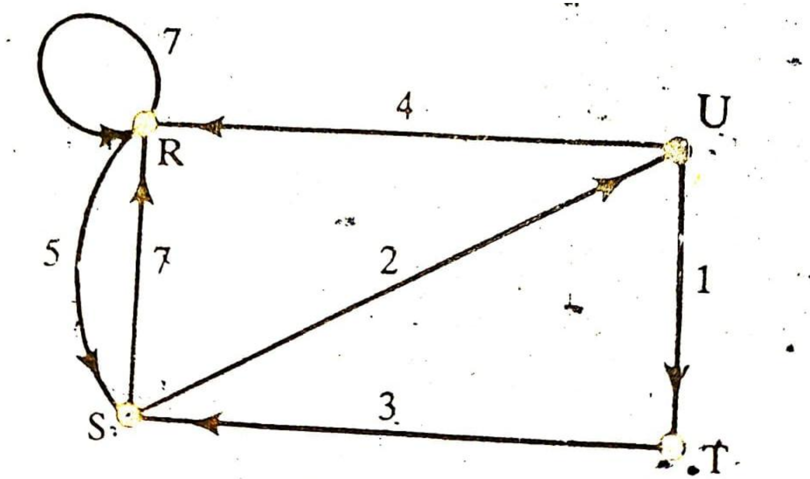
•Applying the modified Warshall's algorithm, we obtain the following matrices:

$$Q_2=\begin{pmatrix} 7 & 5 & \infty & 7 \\ 7 & 12 & \infty & 2 \\ 10 & 3 & \infty & 5 \\ 4 & 9 & 1 & 11 \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & RSU \\ SR & SRS & - & SU \\ TSR & TS & - & TSU \\ UR & URS & UT & URS \end{pmatrix}$$

$$Q_3=\begin{pmatrix} 7 & 5 & \infty & 7 \\ 7 & 12 & \infty & 2 \\ 10 & 3 & \infty & 5 \\ 4 & 4 & 1 & 6 \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & RSU \\ SR & SRS & - & SU \\ TSR & TS & - & TSU \\ UR & UTS & UT & UTSU \end{pmatrix}$$

$$Q_3[4,2]=\mathrm{MIN}(Q_2[4,2],\ Q_2[4,3]+Q_2[3,2])=\mathrm{MIN}(9,3+1)=4$$

Shortest Path Algorithm: Example



$$W = \begin{array}{c c} & \begin{array}{cccc} R & S & T & U \end{array} \\ & \begin{pmatrix} 7 & 5 & 0 & 0 \\ 7 & 0 & 0 & 2 \\ 0 & 3 & 0 & 0 \\ 4 & 0 & 1 & 0 \end{pmatrix} \begin{array}{c} R \\ S \\ T \\ U \end{array} \end{array}$$

•Applying the modified Warshall's algorithm, we obtain the following matrices:

$$Q_3 = \begin{pmatrix} 7 & 5 & \infty & 7 \\ 7 & 12 & \infty & 2 \\ 10 & 3 & \infty & 5 \\ 4 & 4 & 1 & 6 \end{pmatrix} \qquad \begin{pmatrix} RR & RS & - & RSU \\ SR & SRS & - & SU \\ TSR & TS & - & TSU \\ UR & UTS & UT & UTSU \end{pmatrix}$$

$$Q_4 = \begin{array}{c} R \\ S \\ T \\ U \end{array} \begin{pmatrix} 7 & 5 & 8 & 7 \\ 7 & 11 & 3 & 2 \\ 9 & 3 & 6 & 5 \\ 4 & 4 & 1 & 6 \end{pmatrix} \qquad \begin{pmatrix} RR & RS & RSUT & RSU \\ SR & SURS & SUT & SU \\ TSUR & TS & TSUT & TSU \\ UR & UTS & UT & UTSU \end{pmatrix}$$

$$Q_4[3, 1] = \mathrm{MIN}(Q_3[3, 1],\ Q_3[3, 4] + Q_3[4, 1]) = \mathrm{MIN}(10, 5 + 4) = 9$$

Shortest Path Algorithm: Example